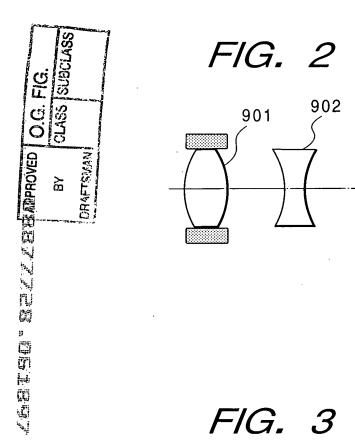
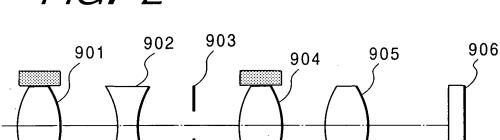


CENTIFICATION O.G. FIG. F/G.

CHAFTSMAN





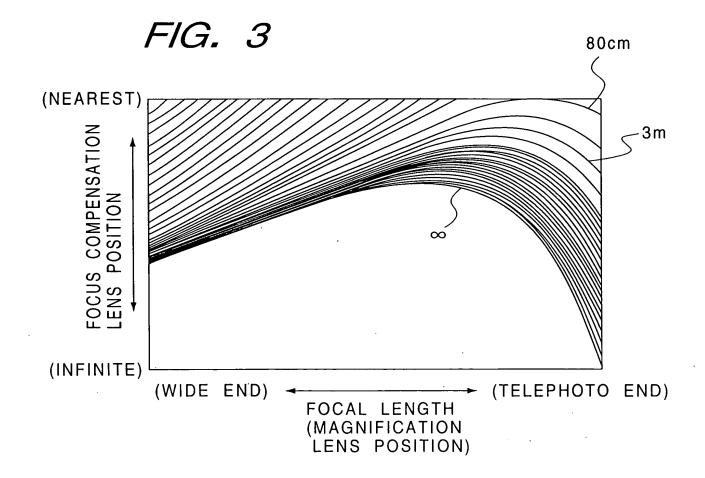




FIG. 4

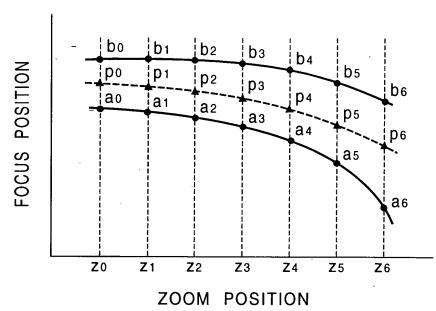
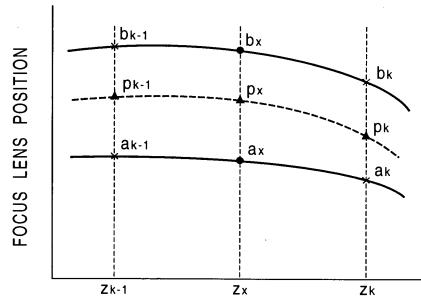


FIG. 5



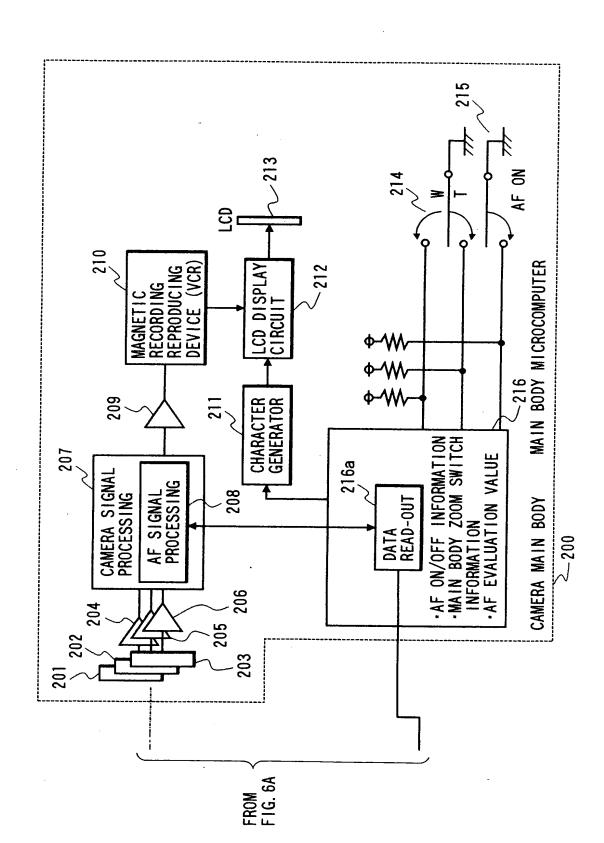
ZOOM LENS POSITION

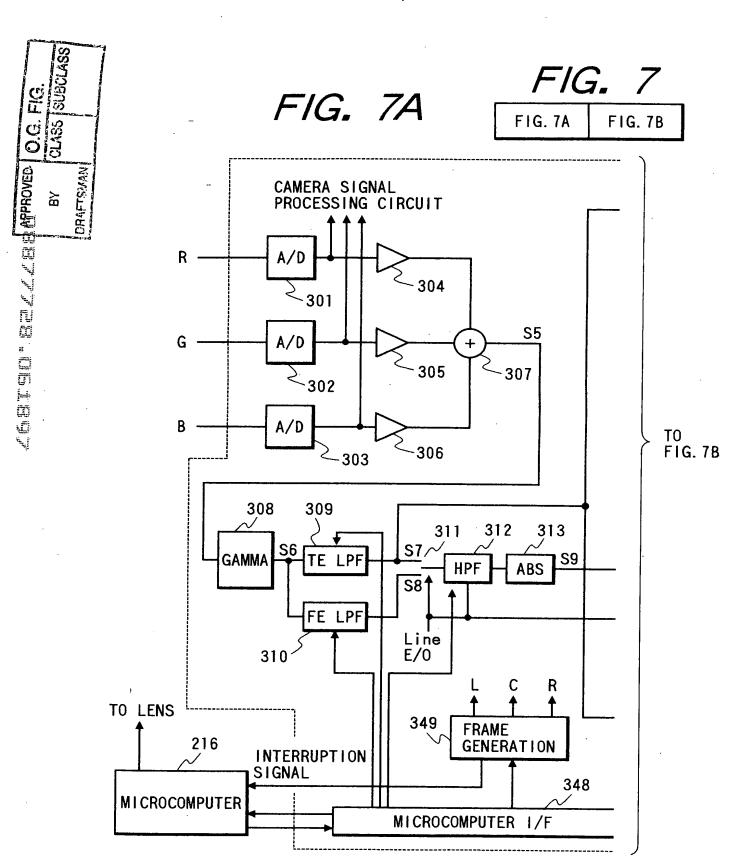
$$ax = ak - \frac{(zk - zk-1)(ak - ak-1)}{(zk - zk-1)}$$

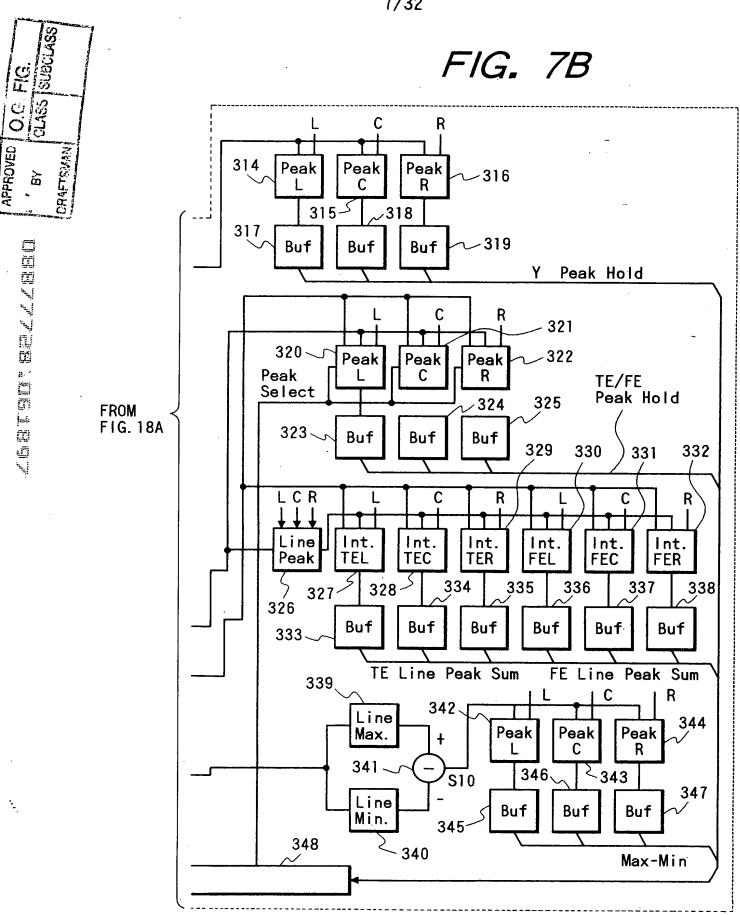
$$bx = bk - \frac{(zk - zx) (bk - bk-1)}{(zk - zk-1)}$$

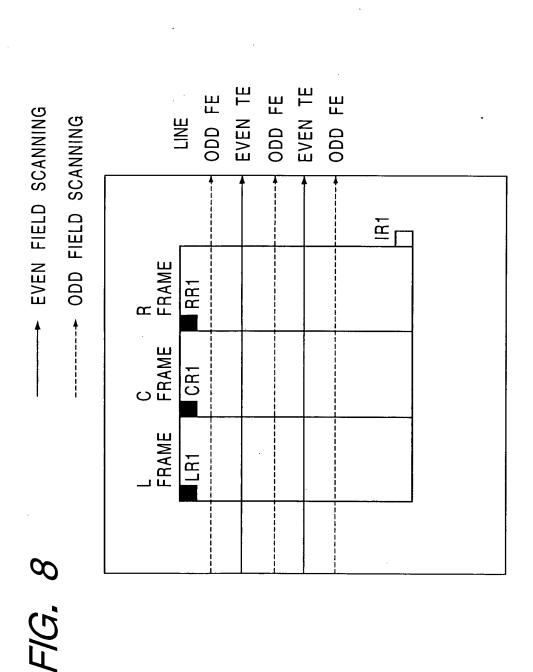


FIG. 6B









APPROVED OG. FIG.

BY CLASS SUBCLASS

☐ TRANSFER OF DATA TO BUFFER, GENERATION OF IRQ RESET OF INTEGRATION CIRCUIT, PEAK-HOLD CIRCUIT



FIG. 9

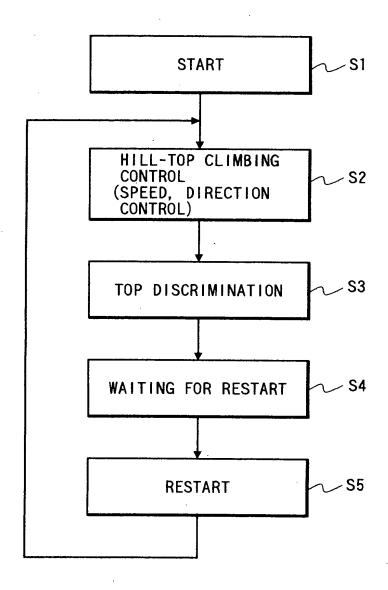
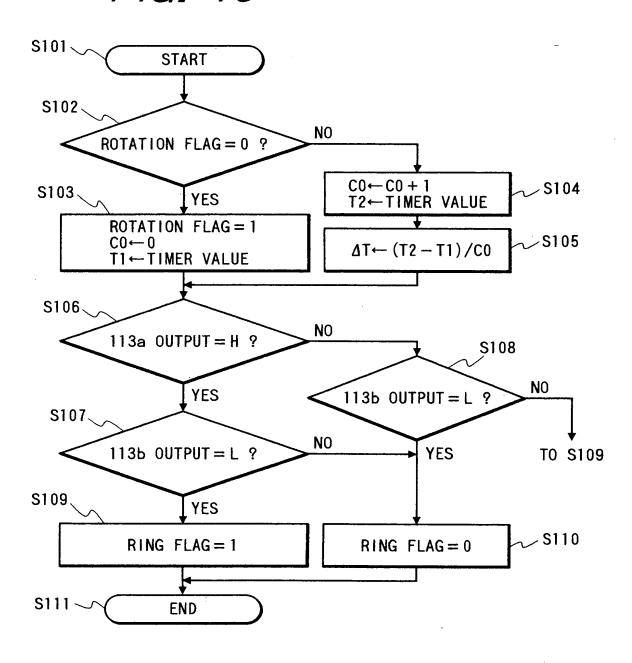




FIG. 10





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FIG. 11

COBTUIN BEZZERUSED OC. FIG. BY CLASS SUBCLASS

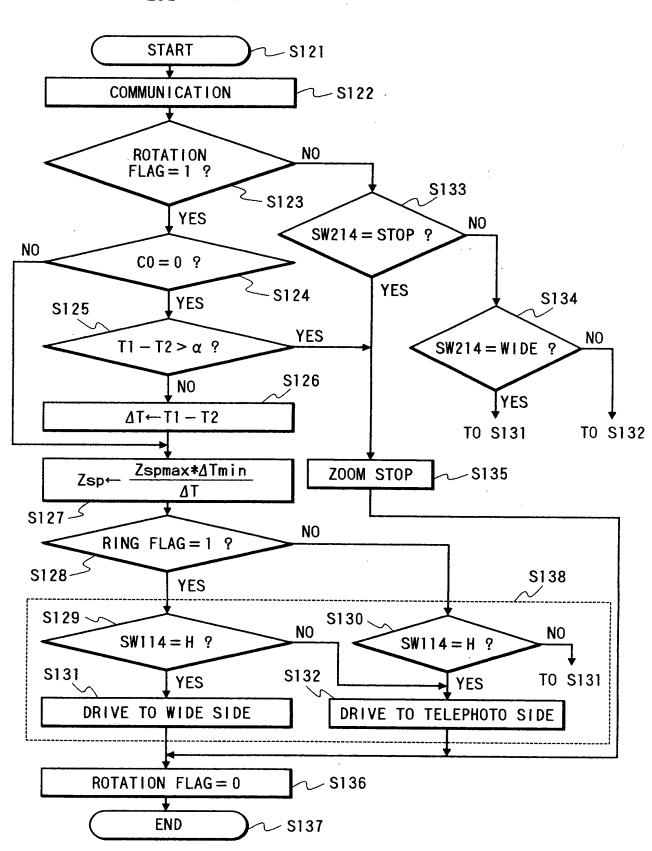




FIG. 12

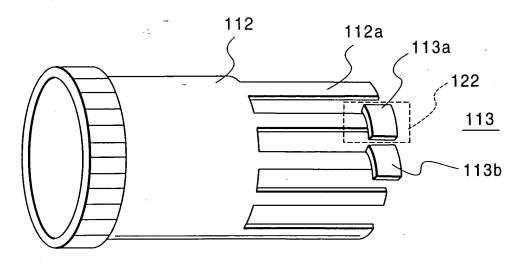
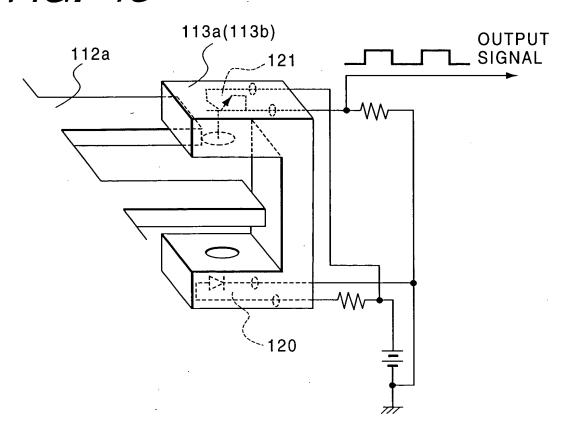


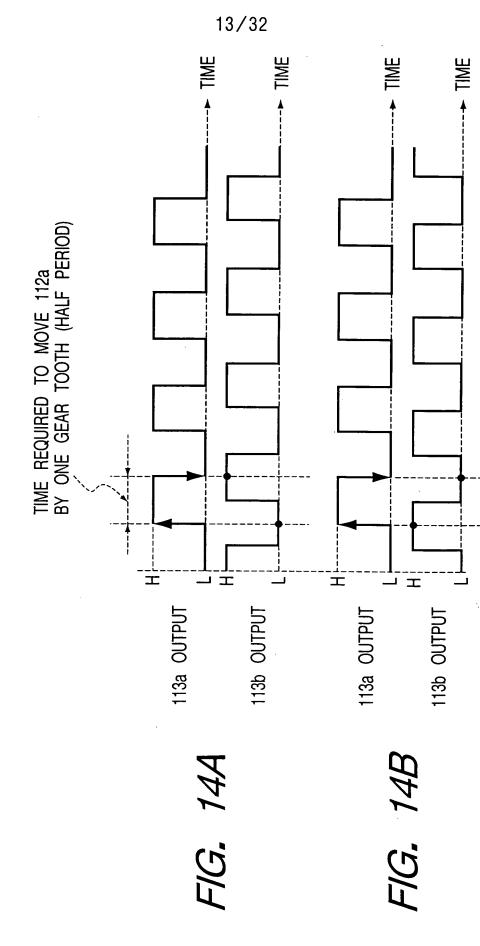
FIG. 13

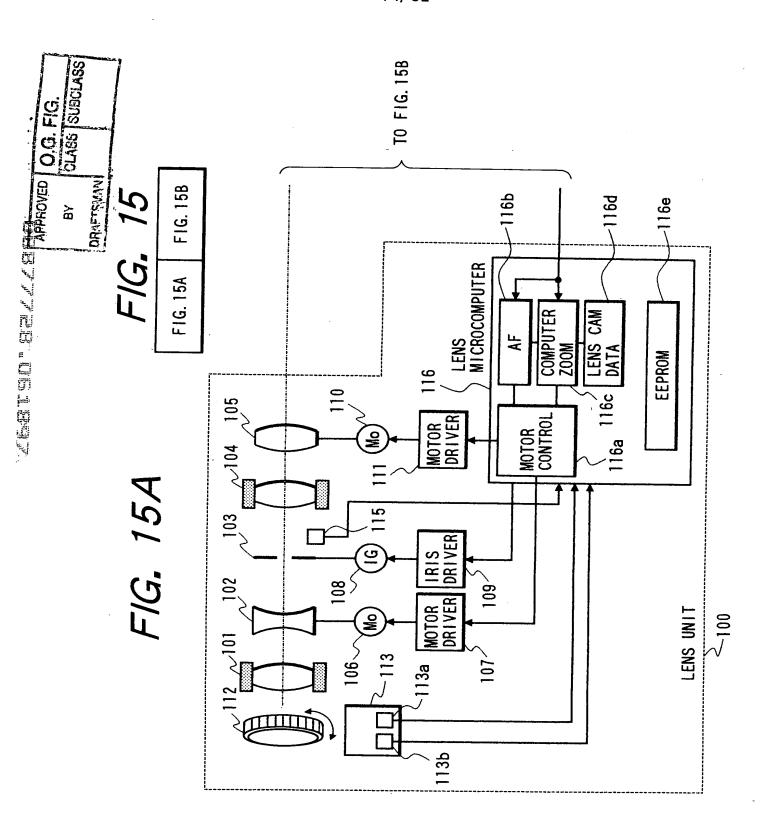


APPROVED O.G. FIG.

BY CLASS SUBCLASS

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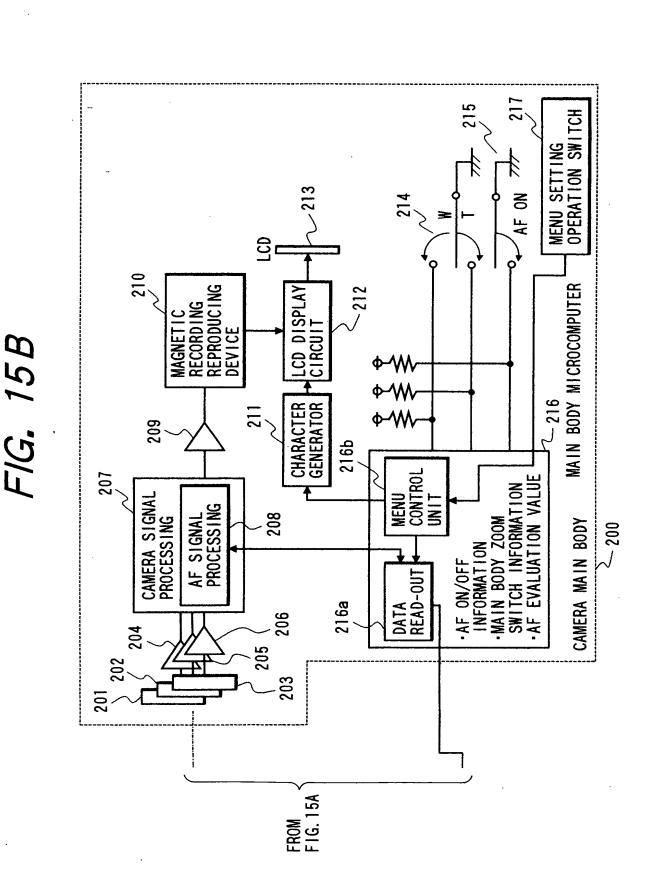




APPROVED O.G. FIG.

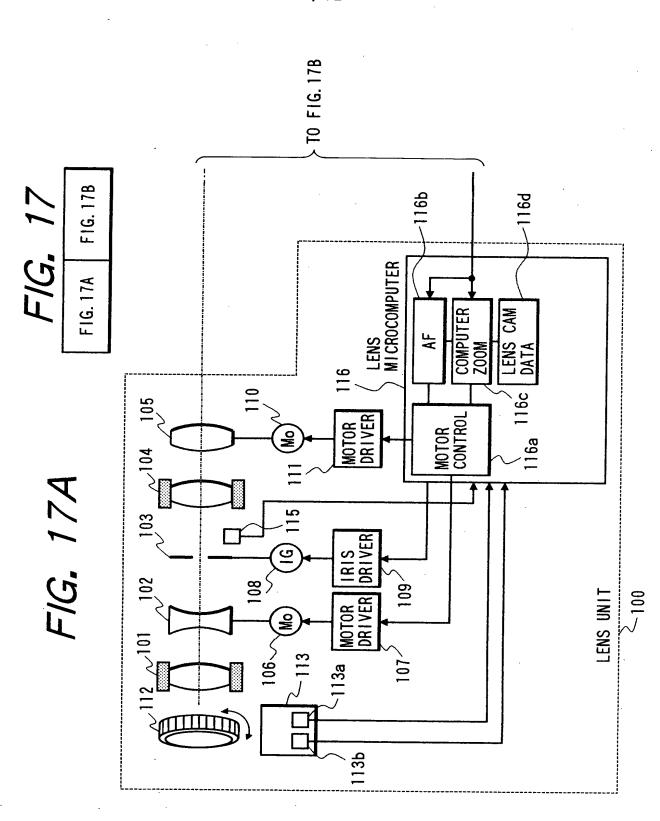
BY CLASS SUBOLASS

CHAFTSMAN



AFFHOVED O.G. FIG.

CHAFTSWAN



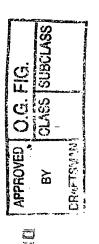
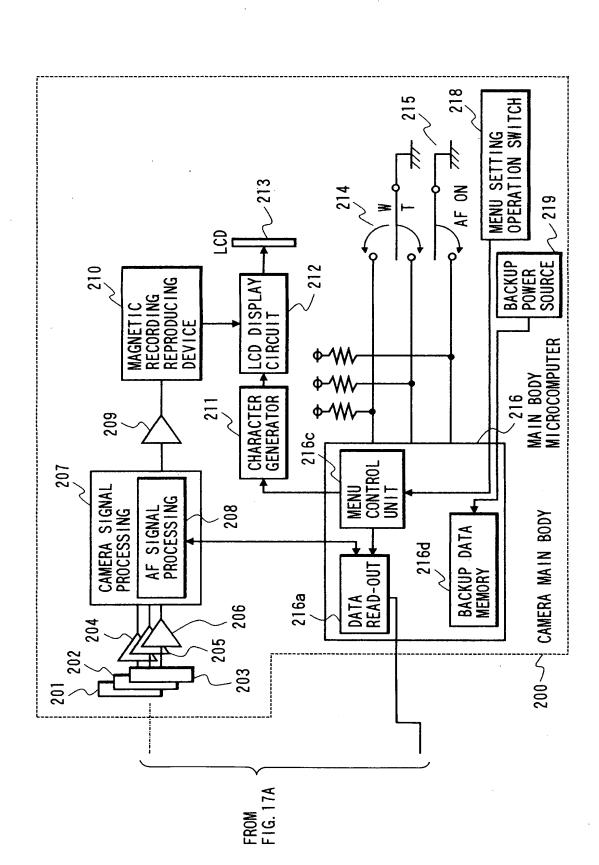
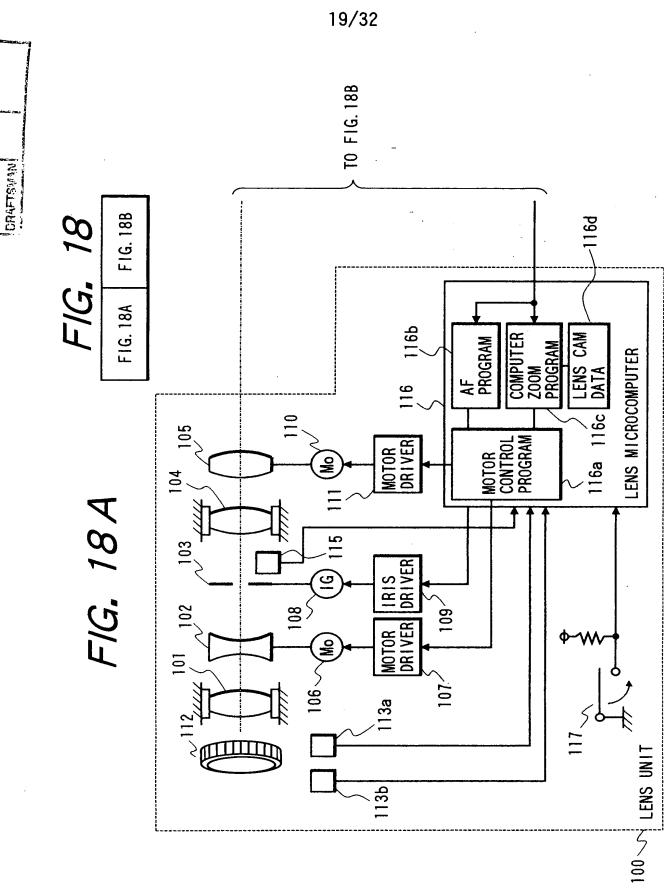


FIG. 17B





APPROVED O.G. FIG. O.B. T. D.A.S. SUBCLASS



FIG. 18B

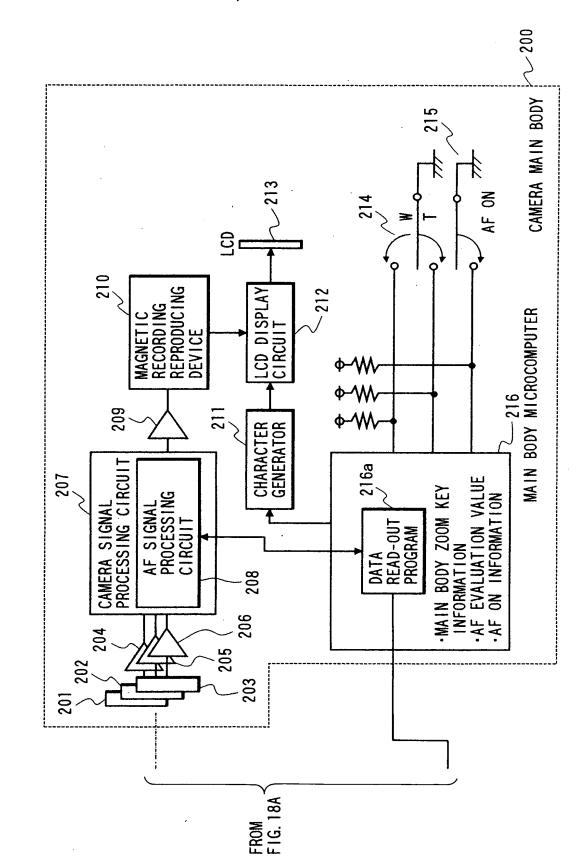
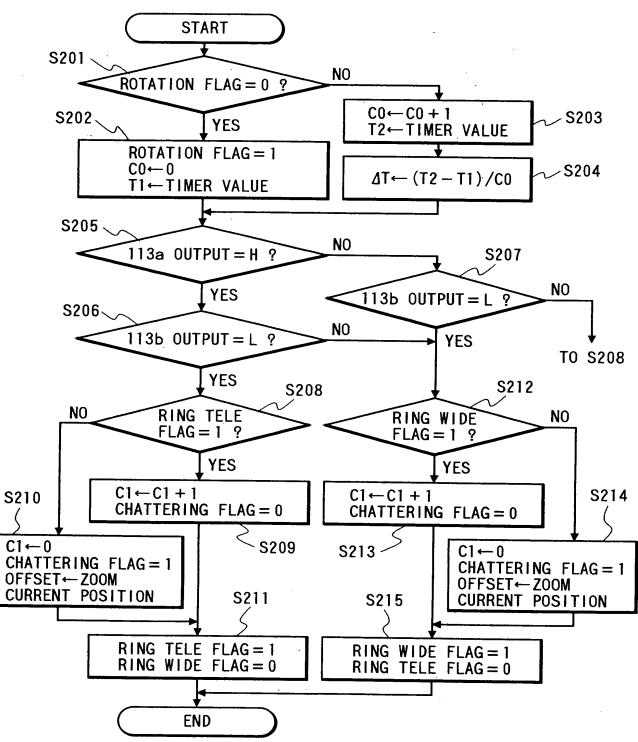
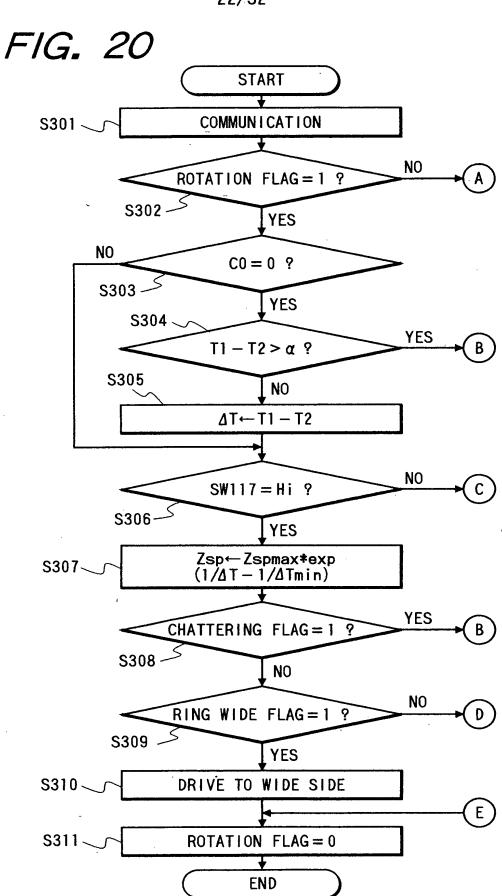


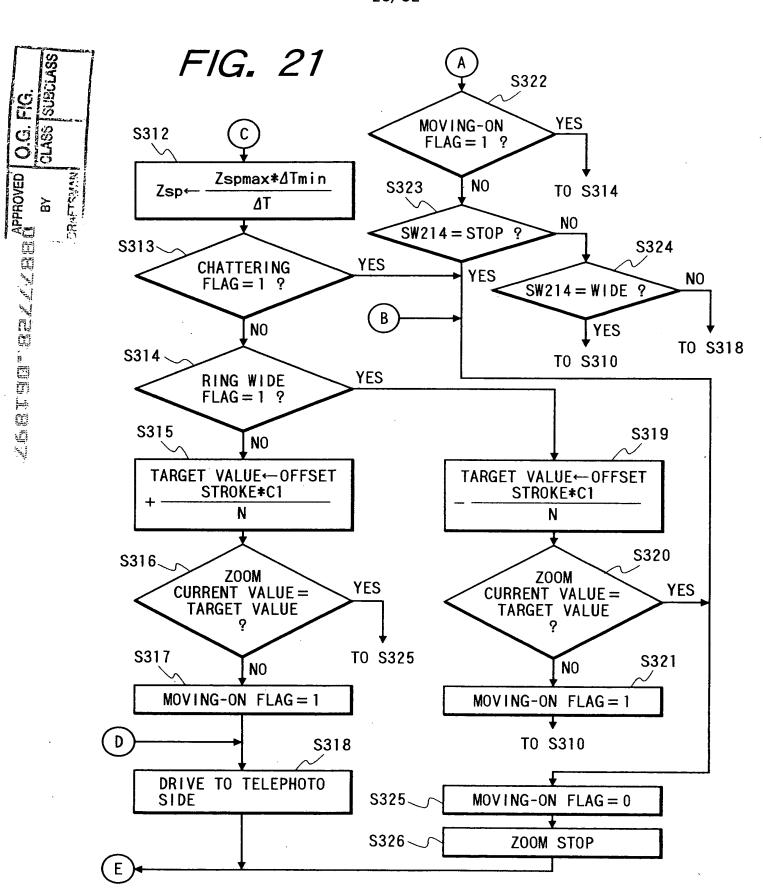


FIG. 19













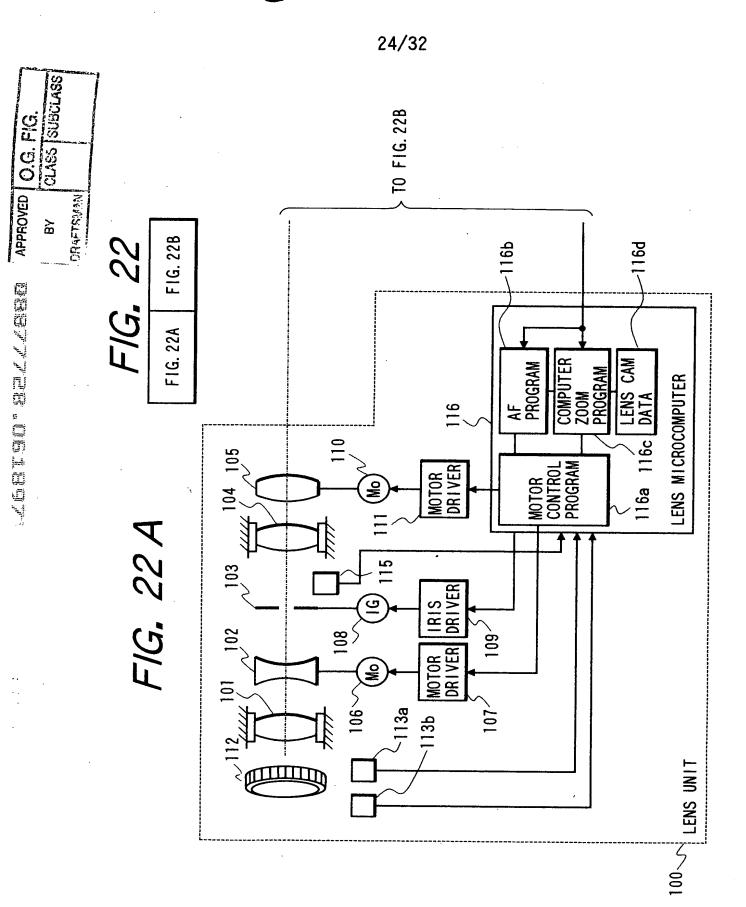
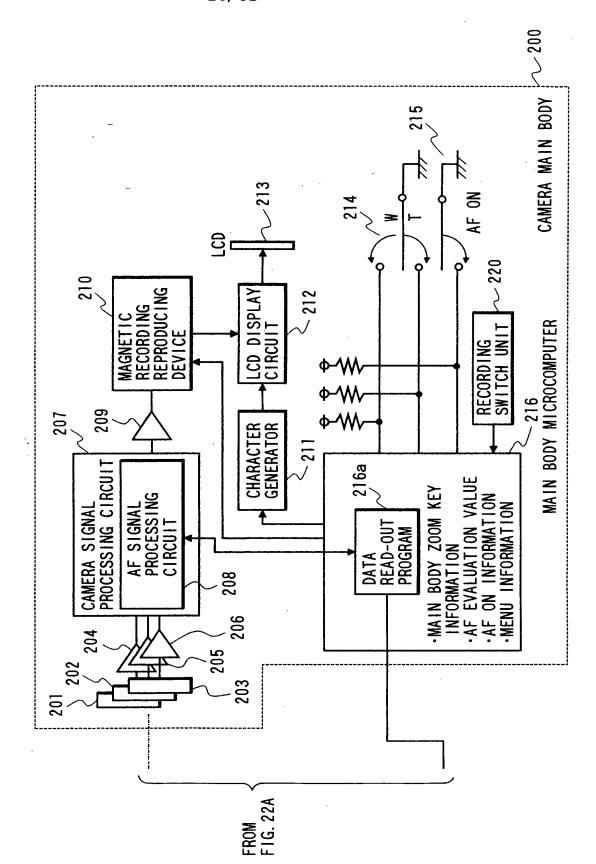




FIG. 22B



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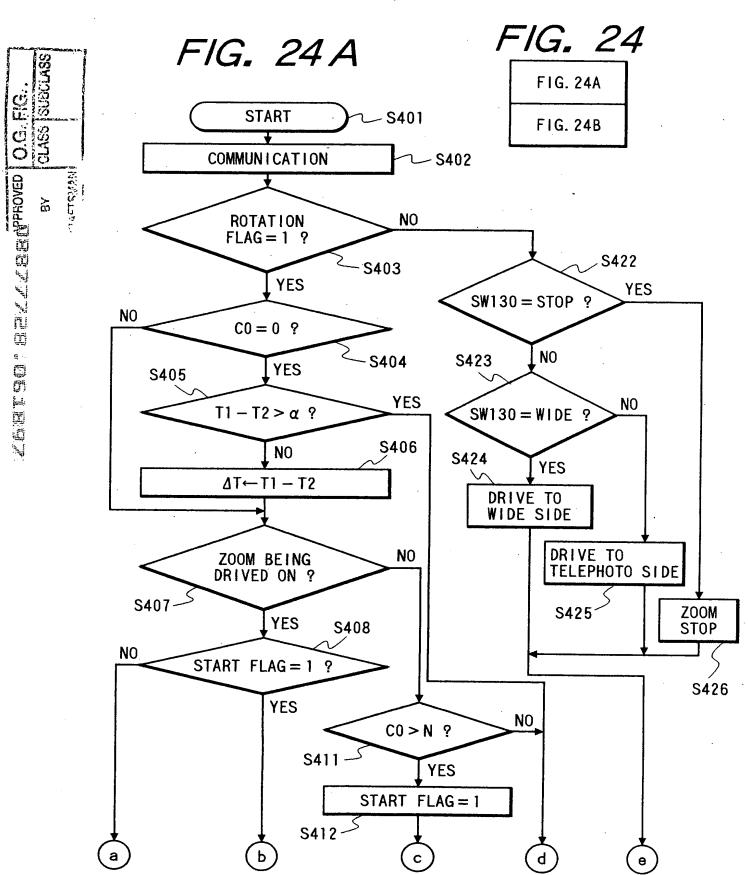
FIG. 23

DETECTION MODULE

CONTROL MODULE



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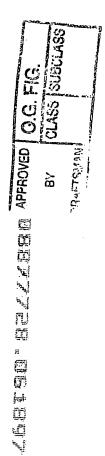
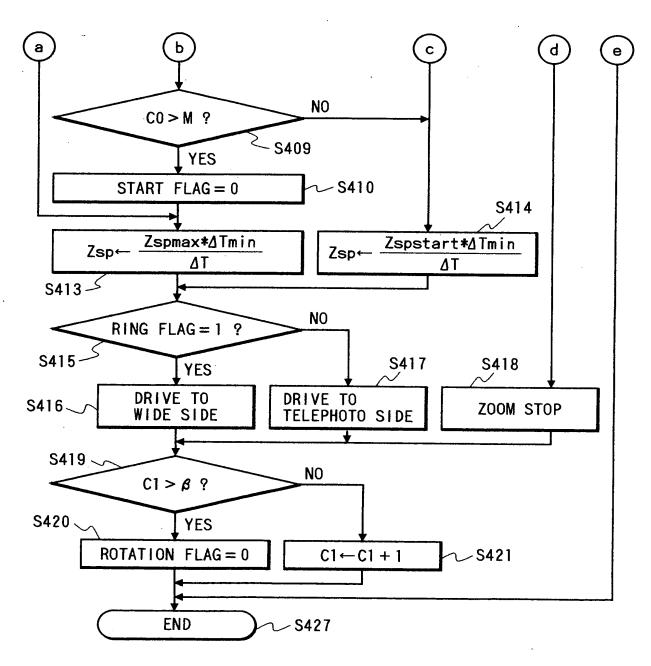
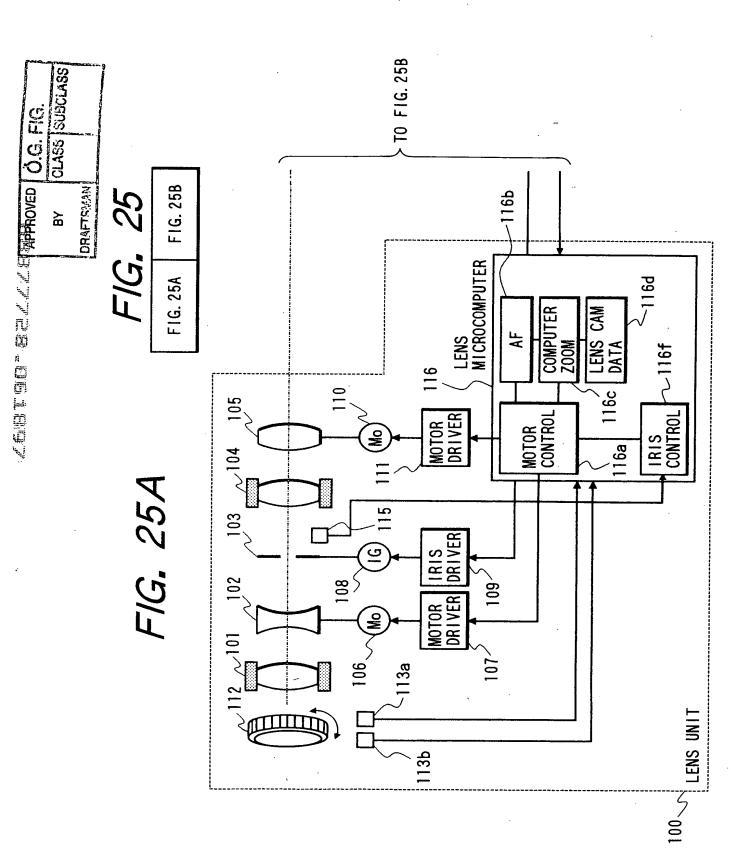


FIG. 24B







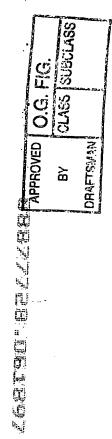
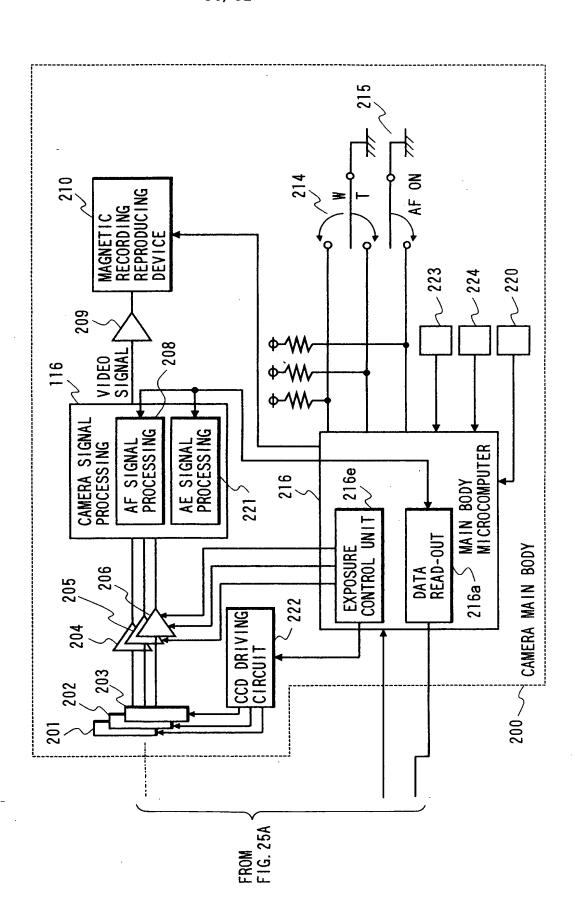
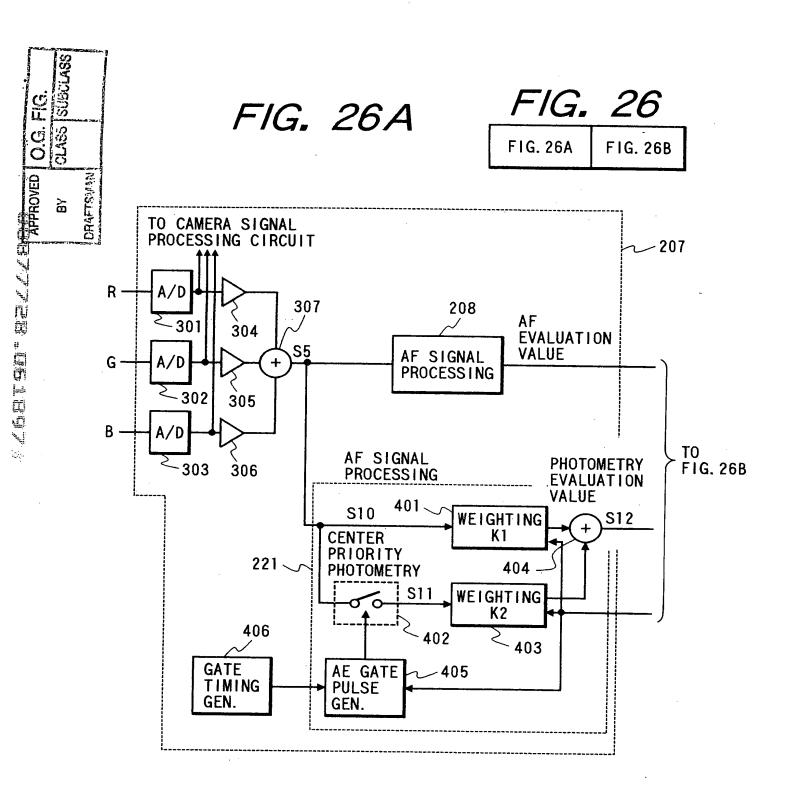


FIG. 25B







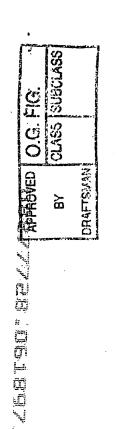


FIG. 26B

